

SL(n)-Covariant L_p -Minkowski Valuations

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Abstract

All continuous SL(n)-covariant L_p -Minkowski valuations defined on convex bodies are completely classified. The L_p -moment body operators turn out to be the nontrivial prototypes of such maps.

1 Introduction

A valuation is a finitely additive function on convex bodies, i.e. nonempty compact convex subsets of \mathbb{R}^n . More general, let \mathcal{Q}^n be a subset of \mathcal{K}^n , the set of convex bodies in \mathbb{R}^n , and let A be an abelian monoid. A map $\Phi: \mathcal{Q}^n \rightarrow A$ is called a valuation, if

$$\Phi(K \cup L) + \Phi(K \cap L) = \Phi(K) + \Phi(L) \quad (1)$$

for all $K, L \in \mathcal{Q}^n$ with $K \cup L, K \cap L \in \mathcal{Q}^n$. At the beginning of the last century Dehn's solution of Hilbert's Third Problem sparked a lot of interest in valuations. In the 1950's Hadwiger started a systematic study of valuations, which resulted in his famous classification of all continuous rigid motion invariant real valued valuations (see e.g. [40]). Numerous results in the spirit of Hadwiger's theorem were established over the last years (see e.g. [1–4, 22, 25, 29, 30, 36]).

Apart from real valued valuations convex body valued valuations are the focus of increased attention (see e.g. [13–15, 17, 20, 24, 26–28, 31, 38, 41, 43, 44, 47]). The simplest way to define an addition on \mathcal{K}^n such that it becomes an abelian monoid is Minkowski addition, i.e. $K + L := \{x + y : x \in K, y \in L\}$ for $K, L \in \mathcal{K}^n$. The corresponding Minkowski valuations and their generalizations attracted a lot of attention in recent years, because they have applications in many areas such as convexity, stochastic geometry, functional analysis and geometric tomography (see e.g. [5–8, 10, 18, 19, 21, 31, 32, 34, 35, 38, 42, 44, 45, 47–50]).

This article focuses on valuations Φ which are SL(n)-covariant, i.e. $\Phi(\phi K) = \phi \Phi K$ for all $K \in \mathcal{K}^n$ and $\phi \in \text{SL}(n)$. Clearly the identity $K \mapsto K$, $K \in \mathcal{K}^n$, and the reflection at the origin $K \mapsto -K$, $K \in \mathcal{K}^n$, are SL(n)-covariant Minkowski valuations. Another important example is the moment body operator $M: \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ defined by

$$h(MK, u) = \int_K |\langle x, u \rangle| dx, \quad u \in \mathbb{R}^n,$$

for all $K \in \mathcal{K}^n$, where \mathcal{K}_o^n denotes the set of convex bodies containing the origin and where $h(K, u) := \max_{x \in K} \langle x, u \rangle$, $u \in \mathbb{R}^n$, is the support function of the convex body K . For a volume normalized convex body this integral can be interpreted as the expectation of a certain mass distribution depending on K and u . Moment bodies (under a different normalization) are also called centroid bodies and were formally defined by Petty [39], but they actually date back to Dupin and Blaschke. The name “centroid body” comes from the fact that for a symmetric convex body K the boundary of MK consists of points which are, up to normalization, the centroids of K intersected with halfspaces. Ludwig [27] showed that the only nontrivial examples of continuous homogeneous $\text{SL}(n)$ -covariant Minkowski valuations on \mathcal{K}_o^n are the moment body operators. Assuming $\text{SL}(n)$ -covariance together with homogeneity is basically assuming $\text{GL}(n)$ -covariance, where one has to take the determinant of $\phi \in \text{GL}(n)$ into account. Once the valuations that were $\text{GL}(n)$ -covariant were understood, the next step was in trying to classify those valuations that were *only* $\text{SL}(n)$ -covariant. This turned out to be difficult, because the involved functional equations were a lot more complicated. A real breakthrough here was first achieved by Haberl in [15], where he removed the assumption on homogeneity in Ludwig’s classification.

A generalization of Minkowski addition is L_p -Minkowski addition (also known as Minkowski-Firey L_p -addition) for $p > 1$, which is defined by

$$h(K +_p L, \cdot)^p = h(K, \cdot)^p + h(L, \cdot)^p \quad (2)$$

for all $K, L \in \mathcal{K}_o^n$, the set of convex bodies containing the origin. The corresponding L_p -Minkowski valuations also received a lot of attention in recent years (see e.g. [5, 7, 9, 12, 16, 19, 27, 32, 33, 35, 37, 48, 49]). In particular, they play an important role in new affine Sobolev inequalities (see e.g. [6, 18, 34, 50]).

The identity and the reflection at the origin, both restricted to \mathcal{K}_o^n , are also $\text{SL}(n)$ -covariant L_p -Minkowski valuations. Furthermore, the (symmetric) L_p -moment body operator $M_p: \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ defined by

$$h(M_p K, u)^p = \int_K |\langle x, u \rangle|^p dx, \quad u \in \mathbb{R}^n$$

for all $K \in \mathcal{K}^n$, which encodes the p -th moment of the aforementioned mass distribution, is an $\text{SL}(n)$ -covariant L_p -Minkowski valuation. For the definitions of the variants M_p^+ and M_p^- see (4). Ludwig [27] also showed that the only nontrivial examples of continuous homogeneous $\text{SL}(n)$ -covariant L_p -Minkowski valuations on \mathcal{K}_o^n are the L_p -moment body operators. Our first main theorem improves this classification by removing the homogeneity assumption.

Theorem. *Let $n \geq 3$. An operator $\Phi: \mathcal{K}_o^n \rightarrow \mathcal{K}_o^n$ is a continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuation, if and only if there exist constants $c_1, c_2, c_3, c_4 \geq 0$ such that*

$$\Phi K = c_1 M_p^+ K +_p c_2 M_p^- K +_p c_3 K +_p c_4 (-K)$$

for all $K \in \mathcal{K}_o^n$.

Wannerer [47] extended Ludwig's characterization from valuations on \mathcal{K}_o^n to valuations on \mathcal{K}^n . In this case four additional operators arise. Our second main theorem characterizes continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuations defined on \mathcal{K}^n . Again, no assumption on homogeneity is needed. In our case only two additional operators arise. For the definitions of \hat{M}_p^+ and \hat{M}_p^- see (5). Furthermore, K_o is defined as the convex hull of a convex body K and the origin.

Theorem. *Let $n \geq 3$. An operator $\Phi: \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ is a continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuation, if and only if there exist constants $c_1, c_2, c_3, c_4, c_5, c_6 \geq 0$ such that*

$$\Phi K = c_1 M_p^+ K +_p c_2 M_p^- K +_p c_3 \hat{M}_p^+ K +_p c_4 \hat{M}_p^- K +_p c_5 K_o +_p c_6 (-K_o)$$

for all $K \in \mathcal{K}^n$.

We remark that a complete classification of all continuous $\text{SL}(n)$ -contravariant L_p -Minkowski valuations was also recently obtained by the author in [37].

2 Background Material

As a general reference for the material in this section see [11, 23, 40]. For the dimension of the Euclidean space \mathbb{R}^n , we will always assume that $n \geq 1$. The standard basis vectors will be denoted by e_1, \dots, e_n and the origin by o . We will often write $x = (x_1, \dots, x_n)^t$ for $x \in \mathbb{R}^n$. For $x, y \in \mathbb{R}^n$ the scalar product, the induced norm and the orthogonal complement will be denoted by $\langle x, y \rangle$, $\|x\|$ and x^\perp , respectively. The linear, affine and convex hull are denoted by lin , aff and conv , respectively. Furthermore we will assume $p > 1$ throughout this article.

Associated with a convex body K is its dimension $\dim K$, which is equal to the dimension of $\text{aff } K$. If K is an m -dimensional convex body we denote its m -dimensional volume by $\text{vol}_m K$. Most of the time we will not work with valuations defined on \mathcal{K}^n or \mathcal{K}_o^n , but with valuations defined on convex polytopes, i.e. convex hulls of finite subsets of \mathbb{R}^n . The set of all convex polytopes is denoted by \mathcal{P}^n and the subset of all convex polytopes containing the origin by \mathcal{P}_o^n .

Apart from Minkowski addition and L_p -Minkowski addition, there is also a scalar multiplication for convex bodies. It is defined by $sK = \{sx : x \in K\}$ for all $K \in \mathcal{K}^n$ and $s \geq 0$. The sets \mathcal{K}^n , \mathcal{K}_o^n , \mathcal{P}^n and \mathcal{P}_o^n are all closed under Minkowski addition and scalar multiplication. Furthermore, the sets \mathcal{K}_o^n and \mathcal{P}_o^n are also closed under L_p -Minkowski addition. When we talk about continuity, we mean continuity with respect to the Hausdorff metric. The Hausdorff distance between two convex bodies K, L is defined by

$$\delta(K, L) = \min\{\epsilon > 0 : K + \epsilon B^n \subseteq L, L + \epsilon B^n \subseteq K\},$$

where B^n is the Euclidean unit ball in \mathbb{R}^n . The sets \mathcal{K}^n and \mathcal{K}_o^n are closed in the Hausdorff topology.

We already mentioned the support function of a convex body in the introduction. A convex body is uniquely defined by its support function. On the other hand, a function

$h: \mathbb{R}^n \rightarrow \mathbb{R}$ is the support function of a convex body, if and only if it is sublinear, i.e.

$$h(u + v) \leq h(u) + h(v) \quad \text{and} \quad h(su) = sh(u)$$

for all $u, v \in \mathbb{R}^n$ and $s > 0$. The first property is called subadditivity and the second is 1-homogeneity. To see that the definition of L_p -Minkowski addition (2) makes sense one just has to verify that $h(K +_p L, \cdot)$ is a nonnegative sublinear function for all $K, L \in \mathcal{K}_o^n$. Note that every sublinear function is convex and therefore continuous.

The map $K \mapsto h(K, \cdot)$ is a homomorphism from \mathcal{K}^n to the space of 1-homogeneous continuous functions on \mathbb{R}^n , denoted $C_1(\mathbb{R}^n)$, i.e.

$$h(K + L, \cdot) = h(K, \cdot) + h(L, \cdot) \quad \text{and} \quad h(sK, \cdot) = sh(K, \cdot)$$

for all $K, L \in \mathcal{K}^n$ and $s \geq 0$. Analogously the map $K \mapsto h(K, \cdot)^p$ is a homomorphism from \mathcal{K}_o^n to the space of p -homogeneous continuous functions on \mathbb{R}^n , denoted $C_p(\mathbb{R}^n)$, i.e.

$$h(K +_p L, \cdot)^p = h(K, \cdot)^p + h(L, \cdot)^p \quad \text{and} \quad h(sK, \cdot)^p = s^p h(K, \cdot)^p$$

for all $K, L \in \mathcal{K}_o^n$ and $s \geq 0$. We can calculate the Hausdorff distance of two convex bodies K, L by $\delta(K, L) = \|h(K, \cdot) - h(L, \cdot)\|_\infty$, where $\|\cdot\|_\infty$ denotes the maximum norm on the Euclidean unit sphere in \mathbb{R}^n , denoted S^{n-1} . Since support functions are homogeneous, they are determined by their values on S^{n-1} . Therefore, it makes sense to equip $C_1(\mathbb{R}^n)$ and $C_p(\mathbb{R}^n)$ with this norm. This also makes the two homomorphisms from above continuous.

We have already defined the notion of valuation in the introduction (1). Note that if \mathcal{Q}^n equals $\mathcal{K}^n, \mathcal{K}_o^n, \mathcal{P}$ or \mathcal{P}_o^n the definition simplifies a little, because in this case $K \cup L \in \mathcal{Q}^n$ implies $K \cap L \in \mathcal{Q}^n$ for all $K, L \in \mathcal{Q}^n$. It is easy to see that a map $\Phi: \mathcal{K}^n \rightarrow \mathcal{K}^n$ is a Minkowski valuation, if and only if the map $K \mapsto h(\Phi K, \cdot)$ from \mathcal{K}^n to $C_1(\mathbb{R}^n)$ is a valuation. Similarly a map $\Phi: \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ is an L_p -Minkowski valuation, if and only if the map $K \mapsto h(\Phi K, \cdot)^p$ from \mathcal{K}^n to $C_p(\mathbb{R}^n)$ is a valuation. The same also holds for valuations defined on $\mathcal{K}_o^n, \mathcal{P}$ or \mathcal{P}_o^n .

We now recall some general results on valuations. The first theorem is due to Volland [46] (see also [23]). Short proofs of the other results can be found in [37].

It is convenient to assume that A contains an identity element denoted 0 and to define that $\Phi(\emptyset) = 0$, even though $\emptyset \notin \mathcal{K}^n$. We will do this throughout this article.

2.1 Theorem. *Let A be an abelian group and let $\Phi: \mathcal{P}^n \rightarrow A$ be a valuation. Then Φ satisfies the inclusion exclusion principle, i.e.*

$$\Phi(P_1 \cup \dots \cup P_m) = \sum_{\emptyset \neq S \subseteq \{1, \dots, m\}} (-1)^{|S|-1} \Phi\left(\bigcap_{i \in S} P_i\right)$$

for all $m \in \mathbb{N}$ and $P_1, \dots, P_m \in \mathcal{P}^n$ with $P_1 \cup \dots \cup P_m \in \mathcal{P}^n$.

The convex hull of $k + 1$ affinely independent points is called a k -dimensional simplex. Special simplices are the n -dimensional standard simplex $T^n := \text{conv}\{o, e_1, \dots, e_n\}$ and $\tilde{T}^{n-1} := \text{conv}\{e_1, \dots, e_n\}$, which is an $(n - 1)$ -dimensional simplex.

2.2 Lemma. *Let A be an abelian group and let $\Phi: \mathcal{P}^n \rightarrow A$ be a valuation. Then Φ is determined by its values on n -dimensional simplices.*

2.3 Lemma. *Let A be an abelian group and let $\Phi: \mathcal{P}_o^n \rightarrow A$ be a valuation. Then Φ satisfies the inclusion exclusion principle, i.e.*

$$\Phi(P_1 \cup \dots \cup P_m) = \sum_{\emptyset \neq S \subseteq \{1, \dots, m\}} (-1)^{|S|-1} \Phi\left(\bigcap_{i \in S} P_i\right)$$

for all $m \in \mathbb{N}$ and $P_1, \dots, P_m \in \mathcal{P}_o^n$ with $P_1 \cup \dots \cup P_m \in \mathcal{P}_o^n$.

2.4 Lemma. *Let A be an abelian group and let $\Phi: \mathcal{P}_o^n \rightarrow A$ be a valuation. Then Φ is determined by its values on n -dimensional simplices with one vertex at the origin and its value on $\{o\}$.*

A valuation is called simple, if $\Phi K = 0$ for all $K \in \mathcal{Q}^n$ with $\dim K < n$.

2.5 Lemma. *Let A be an abelian group and let $\Phi: \mathcal{P}^n \rightarrow A$ be a simple valuation. Then Φ is determined by its values on \mathcal{P}_o^n .*

Finally we recall Cauchy's functional equation

$$f(a+b) = f(a) + f(b) \quad \forall a, b \in \mathbb{R}. \quad (3)$$

Of course every linear function satisfies (3). It is a well known fact that a nonlinear function $f: \mathbb{R} \rightarrow \mathbb{R}$ can only satisfy (3), if it has a dense graph in \mathbb{R}^2 or equivalently if every open subset of \mathbb{R} has a dense image under f . A function $f: (0, +\infty) \rightarrow \mathbb{R}$ satisfying (3) for all $a, b \in (0, +\infty)$ can be extended to an odd function on \mathbb{R} , which then satisfies Cauchy's functional equation for all $a, b \in \mathbb{R}$. Therefore such a function f is either linear or it has the property that every open subset of $(0, +\infty)$ has a dense image under f .

3 $\text{SL}(n)$ -Covariance

Let \mathcal{Q}^n be \mathcal{K}^n , \mathcal{P}^n , \mathcal{K}_o^n or \mathcal{P}_o^n . A map $\Phi: \mathcal{Q}^n \rightarrow \mathcal{K}_o^n$ is called $\text{SL}(n)$ -covariant, if it satisfies

$$\Phi(\phi K) = \phi \Phi K$$

for all $K \in \mathcal{Q}^n$ and $\phi \in \text{SL}(n)$. A map $\Phi: \mathcal{Q}^n \rightarrow C_p(\mathbb{R}^n)$ is called $\text{SL}(n)$ -covariant, if it satisfies

$$\Phi(\phi K) = \Phi(K) \circ \phi^t$$

for all $K \in \mathcal{Q}^n$ and $\phi \in \text{SL}(n)$. Since

$$h(\phi \Phi K, u) = h(\Phi K, \phi^t u)$$

holds for all $K \in \mathcal{Q}^n$, $u \in \mathbb{R}^n$ and $\phi \in \text{SL}(n)$, we see that a map $\Phi: \mathcal{Q}^n \rightarrow \mathcal{K}_o^n$ is $\text{SL}(n)$ -covariant, if and only if $K \mapsto h(\Phi K, \cdot)^p$ from \mathcal{Q}^n to $C_p(\mathbb{R}^n)$ is $\text{SL}(n)$ -covariant. We also make analogous definitions and remarks for the general linear group, $\text{GL}(n)$.

We define an $\text{SL}(n)$ -covariant L_p -Minkowski valuation $I_p^+ : \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ by

$$h(I_p^+ K, \cdot)^p = \max_{x \in K} \langle x, \cdot \rangle_+^p$$

for all $K \in \mathcal{K}^n$, where $\langle x, \cdot \rangle_+ := \max(0, \langle x, \cdot \rangle)$ denotes the positive part of $\langle x, \cdot \rangle$. Note that $I_p^+ K = K_o$ for all $K \in \mathcal{K}^n$. Similarly we define an $\text{SL}(n)$ -covariant L_p -Minkowski valuation $I_p^- : \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ by

$$h(I_p^- K, \cdot)^p = \max_{x \in K} \langle x, \cdot \rangle_-^p$$

for all $K \in \mathcal{K}^n$, where $\langle x, \cdot \rangle_- := \max(0, -\langle x, \cdot \rangle)$ denotes the negative part of $\langle x, \cdot \rangle$. Note that $I_p^- K = -K_o$ for all $K \in \mathcal{K}^n$. There are two other very similar $\text{SL}(n)$ -covariant valuations, namely $J_p^+ : \mathcal{K}^n \rightarrow C_p(\mathbb{R}^n)$ and $J_p^- : \mathcal{K}^n \rightarrow C_p(\mathbb{R}^n)$. These are defined by

$$J_p^+ K = \min_{x \in K} \langle x, \cdot \rangle_+^p$$

for all $K \in \mathcal{K}^n$ and by

$$J_p^- K = \min_{x \in K} \langle x, \cdot \rangle_-^p$$

for all $K \in \mathcal{K}^n$, respectively. Note that $J_p^+ K$ and $J_p^- K$ are not necessarily support functions of convex bodies. Also note that J_p^+ and J_p^- vanish on \mathcal{K}_o^n . Finally we remark that I_p^+ , I_p^- , J_p^+ and J_p^- are also continuous and $\text{GL}(n)$ -covariant.

Another family of $\text{SL}(n)$ -covariant L_p -Minkowski valuations are the L_p -moment body operators. We define $M_p^+ : \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ by

$$h(M_p^+ K, \cdot)^p = \int_K \langle x, \cdot \rangle_+^p dx \quad (4)$$

for all $K \in \mathcal{K}^n$. Similarly we define $M_p^- : \mathcal{K}^n \rightarrow \mathcal{K}_o^n$. Note that M_p^+ and M_p^- are simple. A variant of M_p^+ is $\hat{M}_p^+ : \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ defined by

$$h(\hat{M}_p^+ K, \cdot)^p = \int_{K_o \setminus K} \langle x, \cdot \rangle_+^p dx \quad (5)$$

for all $K \in \mathcal{K}^n$. Similarly we define $\hat{M}_p^- : \mathcal{K}^n \rightarrow \mathcal{K}_o^n$. Note that \hat{M}_p^+ and \hat{M}_p^- vanish on \mathcal{K}_o^n . Finally we remark that M_p^+ , M_p^- , \hat{M}_p^+ and \hat{M}_p^- are also continuous and $(n+p)/p$ -homogeneous.

If we view \mathcal{K}_o^n as a subset of $C_p(\mathbb{R}^n)$, then we have defined eight linearly independent $\text{SL}(n)$ -covariant valuations with values in $C_p(\mathbb{R}^n)$. Notice that evaluating the minus-version of one of these operators at K is the same as evaluating the plus-version at $-K$, for example $I_p^- K = I_p^+(-K)$.

For later use we need to calculate some constants. Let $i \in \{1, \dots, n\}$. We start with

$$h(I_p^+[o, e_i], x)^p = \max_{y \in [o, e_i]} \langle y, x \rangle_+^p = \langle e_i, x \rangle_+^p = (x_i)_+^p \quad (6)$$

for all $x \in \mathbb{R}^n$.

Next we calculate

$$\begin{aligned}
h\left(M_p^+ T^n, e_i\right)^p &= \int_{T^n} \langle x, e_i \rangle_+^p dx \\
&= \int_0^1 x_i^p \text{vol}_{n-1}\left((1-x_i)T^{n-1}\right) dx_i \\
&= \text{vol}_{n-1}\left(T^{n-1}\right) \int_0^1 x_i^p (1-x_i)^{n-1} dx_i \\
&= \frac{1}{(n-1)!} B(p+1, n) \\
&= \frac{\Gamma(p+1)\Gamma(n)}{(n-1)! \Gamma(p+1+n)} \\
&= \frac{\Gamma(p+1)}{\Gamma(p+1+n)},
\end{aligned} \tag{7}$$

where B and Γ denote the Beta function and the Gamma function, respectively. Obviously we have

$$h\left(M_p^+ T^n, -e_i\right)^p = 0. \tag{8}$$

Now we will calculate some constants which will be used in the classification of valuations on \mathcal{P}^n . Let $i \in \{1, \dots, n\}$. We start with

$$h\left(I_p^+[e_i, 2e_i], x\right)^p = \max_{y \in [e_i, 2e_i]} \langle y, x \rangle_+^p = \langle 2e_i, x \rangle_+^p = 2^p (x_i)_+^p \tag{9}$$

for all $x \in \mathbb{R}^n$. Analogously we see that

$$J_p^+([e_i, 2e_i])(x) = (x_i)_+^p. \tag{10}$$

Next we calculate

$$h\left(\hat{M}_p^+ \tilde{T}^{n-1}, e_i\right)^p = h\left(M_p^+ T^n, e_i\right)^p = \frac{\Gamma(p+1)}{\Gamma(p+1+n)} \tag{11}$$

and

$$h\left(\hat{M}_p^+ \tilde{T}^{n-1}, -e_i\right)^p = 0. \tag{12}$$

Now let $n \geq 2$. We set $K = \text{conv}\{e_1, e_2, e_1 + e_2\}$ and calculate:

$$\begin{aligned}
h\left(I_p^+ K, e_1\right)^p &= 1, \quad h\left(I_p^+ K, e_2\right)^p = 1, \quad h\left(I_p^+ K, e_1 + e_2\right)^p = 2^p, \\
J_p^+(K)(e_1) &= 0, \quad J_p^+(K)(e_2) = 0, \quad J_p^+(K)(e_1 + e_2) = 1.
\end{aligned} \tag{13}$$

The values of $h\left(I_p^- K, \cdot\right)^p$ and $J_p^- K$ in these directions are all equal to 0. Finally we compute:

$$\begin{aligned} h\left(I_p^+ \tilde{T}^1, e_1\right)^p &= 1, & h\left(I_p^+ \tilde{T}^1, e_1 + e_2\right)^p &= 1, & h\left(I_p^+ \tilde{T}^1, 2e_1 + e_2\right)^p &= 2^p, \\ J_p^+(\tilde{T}^1)(e_1) &= 0, & J_p^+(\tilde{T}^1)(e_1 + e_2) &= 1, & J_p^+(\tilde{T}^1)(2e_1 + e_2) &= 1. \end{aligned} \quad (14)$$

The values of $h\left(I_p^- \tilde{T}^1, \cdot\right)^p$ and $J_p^- \tilde{T}^1$ in these directions are all equal to 0.

In \mathbb{R}^2 there are other $\text{SL}(n)$ -covariant valuations, which do not show up in \mathbb{R}^n for $n \geq 3$. We will only cover those additional operators in \mathbb{R}^2 that we need for the proof of the $n \geq 3$ case. We define $E_p^+ : \mathcal{K}^2 \rightarrow \mathcal{K}_o^2$ by

$$h\left(E_p^+ K, \cdot\right)^p = \frac{1}{2} \sum_{\substack{u \in S^1 \\ h(K, u) = 0}} \max_{x \in F(K, u)} \langle x, \cdot \rangle_+^p$$

for all $K \in \mathcal{K}^n$, where $F(K, u) := \{x \in K : \langle x, u \rangle = h(K, u)\}$. Note that this sum has at most two nonzero summands. Clearly E_p^+ is $\text{GL}(n)$ -covariant. The valuation property can be shown by a case-by-case analysis. Similarly we define $E_p^- : \mathcal{K}^2 \rightarrow \mathcal{K}_o^2$. It is easy to see that E_p^+ and E_p^- coincide with I_p^+ and I_p^- , respectively, for 1-dimensional convex bodies K with $o \in \text{aff } K$.

Finally $F_p^+ : \mathcal{K}^2 \rightarrow C_p(\mathbb{R}^2)$ is defined by

$$F_p^+ K = \frac{1}{2} \sum_{\substack{u \in S^1 \\ h(K, u) = 0}} \min_{x \in F(K, u)} \langle x, \cdot \rangle_+^p$$

for all $K \in \mathcal{K}^n$. Similarly we define $F_p^- : \mathcal{K}^2 \rightarrow C_p(\mathbb{R}^2)$. Note that $F_p^+ K$ and $F_p^- K$ are not necessarily support functions of convex bodies. Also note that F_p^+ and F_p^- vanish on \mathcal{K}_o^n . It is easy to see that F_p^+ and F_p^- coincide with J_p^+ and J_p^- , respectively, for 1-dimensional convex bodies K with $o \in \text{aff } K$. Notice again how one can get the minus-version of an operator by inserting $-K$ in the plus-version.

We will now collect some properties of these new valuations in \mathbb{R}^2 and calculate some constants. Let $i \in \{1, 2\}$. We start with calculating

$$h\left(E_p^+ T^2, e_i\right)^p = \frac{1}{2} (h([0, e_1], e_i)^p + h([0, e_2], e_i)^p) = \frac{1}{2}.$$

Similarly we have

$$h\left(E_p^+ T^2, -e_i\right)^p = 0.$$

Therefore we get:

$$\begin{aligned} h\left(I_p^+ T^2, e_i\right)^p - h\left(E_p^+ T^2, e_i\right)^p &= 1 - \frac{1}{2} = \frac{1}{2}, \\ h\left(I_p^+ T^2, -e_i\right)^p - h\left(E_p^+ T^2, -e_i\right)^p &= 0 - 0 = 0. \end{aligned} \quad (15)$$

Next, we will look at the continuity of the above operators. Clearly

$$\lim_{\varepsilon \rightarrow 0} [-\varepsilon e_1, e_1] + [-\varepsilon e_2, \varepsilon e_2] = [0, e_1].$$

Since

$$\begin{aligned} & \lim_{\varepsilon \rightarrow 0} h \left(\mathbf{I}_p^+ ([-\varepsilon e_1, e_1] + [-\varepsilon e_2, \varepsilon e_2]), e_1 \right)^p - h \left(\mathbf{E}_p^+ ([-\varepsilon e_1, e_1] + [-\varepsilon e_2, \varepsilon e_2]), e_1 \right)^p \\ &= \lim_{\varepsilon \rightarrow 0} h \left([-\varepsilon e_1, e_1] + [-\varepsilon e_2, \varepsilon e_2], e_1 \right)^p \\ &= h \left([0, e_1], e_1 \right)^p \\ &= 1 \end{aligned}$$

and since

$$h \left(\mathbf{I}_p^+ [0, e_1], e_1 \right)^p - h \left(\mathbf{E}_p^+ [0, e_1], e_1 \right)^p = 0,$$

we see that

$$P \mapsto h \left(\mathbf{I}_p^+ P, \cdot \right)^p - h \left(\mathbf{E}_p^+ P, \cdot \right)^p$$

from \mathcal{P}_o^n to $C_p(\mathbb{R}^n)$ is not continuous at $[0, e_1]$. Similarly we prove the following lemma.

3.1 Lemma. *The only linear combination of*

$$P \mapsto h \left(\mathbf{I}_p^+ P, \cdot \right)^p - h \left(\mathbf{E}_p^+ P, \cdot \right)^p \quad \text{and} \quad P \mapsto h \left(\mathbf{I}_p^- P, \cdot \right)^p - h \left(\mathbf{E}_p^- P, \cdot \right)^p$$

which is continuous at $[0, e_1]$ is the trivial one.

Finally we need to calculate some constants related to valuations on \mathcal{P}^2 . Let $i \in \{1, 2\}$. We start with

$$h \left(\mathbf{E}_p^+ \tilde{T}^1, e_i \right)^p = \frac{1}{2} \left(\langle e_1, e_i \rangle_+^p + \langle e_2, e_i \rangle_+^p \right) = \frac{1}{2}.$$

Similarly we have

$$h \left(\mathbf{E}_p^+ \tilde{T}^1, -e_i \right)^p = 0.$$

Therefore we get:

$$\begin{aligned} h \left(\mathbf{I}_p^+ \tilde{T}^1, e_i \right)^p - h \left(\mathbf{E}_p^+ \tilde{T}^1, e_i \right)^p &= 1 - \frac{1}{2} = \frac{1}{2}, \\ h \left(\mathbf{I}_p^+ \tilde{T}^1, -e_i \right)^p - h \left(\mathbf{E}_p^+ \tilde{T}^1, -e_i \right)^p &= 0 - 0 = 0. \end{aligned} \tag{16}$$

Analogously we calculate:

$$\begin{aligned} h \left(\mathbf{I}_p^+ T^2, e_i \right)^p - h \left(\mathbf{E}_p^+ T^2, e_i \right)^p + \mathbf{J}_p^+(T^2)(e_i) - \mathbf{F}_p^+(T^2)(e_i) &= \frac{1}{2}, \\ h \left(\mathbf{I}_p^+ T^2, -e_i \right)^p - h \left(\mathbf{E}_p^+ T^2, -e_i \right)^p + \mathbf{J}_p^+(T^2)(-e_i) - \mathbf{F}_p^+(T^2)(-e_i) &= 0. \end{aligned} \tag{17}$$

Similar to the proof of Lemma 3.1 we see that the only linear combination of the four operators

$$\begin{aligned} P &\mapsto h\left(I_p^+ P, \cdot\right)^p - h\left(E_p^+ P, \cdot\right)^p, \\ P &\mapsto h\left(I_p^- P, \cdot\right)^p - h\left(E_p^- P, \cdot\right)^p, \\ P &\mapsto h\left(I_p^+ P, \cdot\right)^p - h\left(E_p^+ P, \cdot\right)^p + J_p^+ P - F_p^+ P \end{aligned}$$

and

$$P \mapsto h\left(I_p^- P, \cdot\right)^p - h\left(E_p^- P, \cdot\right)^p + J_p^- P - F_p^- P$$

which is continuous at $[o, e_1]$ is actually a linear combination of $J_p^+ - F_p^+$ and $J_p^- - F_p^-$. Clearly

$$\lim_{\varepsilon \rightarrow 0} \varepsilon e_2 + [o, e_1] = [0, e_1].$$

Since

$$\lim_{\varepsilon \rightarrow 0} (J_p^+ - F_p^+)(\varepsilon e_2 + [o, e_1])(e_1) = \lim_{\varepsilon \rightarrow 0} 0 - \frac{1}{2} = -\frac{1}{2}$$

and since

$$(J_p^+ - F_p^+)([0, e_1])(e_1) = 0,$$

we see that $J_p^+ - F_p^+$ is not continuous at $[o, e_1]$. Similarly we see that the only linear combination of the operators $J_p^+ - F_p^+$ and $J_p^- - F_p^-$ which is continuous at $[0, e_1]$ is the trivial one. Therefore we arrive at the following lemma.

3.2 Lemma. *The only linear combination of*

$$\begin{aligned} P &\mapsto h\left(I_p^+ P, \cdot\right)^p - h\left(E_p^+ P, \cdot\right)^p, \\ P &\mapsto h\left(I_p^- P, \cdot\right)^p - h\left(E_p^- P, \cdot\right)^p, \\ P &\mapsto h\left(I_p^+ P, \cdot\right)^p - h\left(E_p^+ P, \cdot\right)^p + J_p^+ P - F_p^+ P \end{aligned}$$

and

$$P \mapsto h\left(I_p^- P, \cdot\right)^p - h\left(E_p^- P, \cdot\right)^p + J_p^- P - F_p^- P$$

which is continuous at $[o, e_1]$ is the trivial one.

We complete this section with a simple lemma (cf. [37]).

3.3 Lemma. *Let \mathcal{Q}^n be either \mathcal{P}_o^n or \mathcal{P}^n and let $\Phi: \mathcal{Q}^n \rightarrow C_p(\mathbb{R}^n)$ be $\text{SL}(n)$ -covariant. Furthermore let $\phi \in \text{GL}(n)$ with $\det \phi > 0$. Then*

$$\Phi(\phi P) = \det(\phi)^{-\frac{p}{n}} \Phi\left(\det(\phi)^{\frac{1}{n}} P\right) \circ \phi^t$$

for all $P \in \mathcal{Q}^n$.

Proof. Since $\det(\phi)^{-\frac{1}{n}} \phi \in \text{SL}(n)$, this follows directly from the $\text{SL}(n)$ -covariance of Φ and the p -homogeneity of the functions in $C_p(\mathbb{R}^n)$. \square

4 Main Results on \mathcal{K}_o^n

The goal of this section is the classification of all continuous $\mathrm{SL}(n)$ -covariant L_p -Minkowski valuations on \mathcal{K}_o^n . It will be convenient to first prove a slightly more general theorem about valuations from \mathcal{P}_o^n to $C_p(\mathbb{R}^n)$. We begin by proving a classification with the additional assumption of simplicity. The next theorem is an adaptation of a corresponding theorem concerning $\mathrm{SL}(n)$ -contravariant valuations from [37].

4.1 Theorem. *Let $n \geq 3$ and let $\Phi: \mathcal{P}_o^n \rightarrow C_p(\mathbb{R}^n)$ be a simple $\mathrm{SL}(n)$ -covariant valuation. Assume further that for every $y \in \mathbb{R}^n$ there exists a bounded open interval $I_y \subseteq (0, +\infty)$ such that $\{\Phi(sT^n)(y) : s \in I_y\}$ is not dense in \mathbb{R} . Then there exist constants $c_1, c_2 \in \mathbb{R}$ such that*

$$\Phi P = c_1 h \left(M_p^+ P, \cdot \right)^p + c_2 h \left(M_p^- P, \cdot \right)^p \quad (18)$$

for all $P \in \mathcal{P}_o^n$.

Proof. Using Lemma 3.3 and Lemma 2.4 it is enough to prove

$$\Phi(sT^n) = c_1 h \left(M_p^+(sT^n), \cdot \right)^p + c_2 h \left(M_p^-(sT^n), \cdot \right)^p \quad (19)$$

for $s > 0$.

1. Functional Equation: Let $\lambda \in (0, 1)$ and denote by H_λ the hyperplane through o with normal vector $\lambda e_1 - (1 - \lambda)e_2$. Since Φ is a valuation we get

$$\Phi(sT^n) + \Phi(sT^n \cap H_\lambda) = \Phi(sT^n \cap H_\lambda^+) + \Phi(sT^n \cap H_\lambda^-),$$

where H_λ^+ and H_λ^- are the two halfspaces bounded by H_λ . Because Φ is assumed to be simple, we get

$$\Phi(sT^n) = \Phi(sT^n \cap H_\lambda^+) + \Phi(sT^n \cap H_\lambda^-). \quad (20)$$

Define $\phi_\lambda \in \mathrm{GL}(n)$ by

$$\phi_\lambda e_1 = e_1, \quad \phi_\lambda e_2 = (1 - \lambda)e_1 + \lambda e_2, \quad \phi_\lambda e_k = e_k \quad \text{for } 3 \leq k \leq n$$

and $\psi_\lambda \in \mathrm{GL}(n)$ by

$$\psi_\lambda e_1 = (1 - \lambda)e_1 + \lambda e_2, \quad \psi_\lambda e_2 = e_2, \quad \psi_\lambda e_k = e_k \quad \text{for } 3 \leq k \leq n.$$

Note that

$$\det(\phi_\lambda) = \lambda \quad \text{and} \quad \det(\psi_\lambda) = 1 - \lambda. \quad (21)$$

Since

$$T^n \cap H_\lambda^+ = \phi_\lambda T^n \quad \text{and} \quad T^n \cap H_\lambda^- = \psi_\lambda T^n,$$

Equation (20) becomes

$$\Phi(sT^n) = \Phi(\phi_\lambda sT^n) + \Phi(\psi_\lambda sT^n).$$

Using Lemma 3.3 and (21) we can rewrite the last equation as

$$\Phi(sT^n)(x) = \lambda^{-\frac{p}{n}} \Phi\left(\lambda^{\frac{1}{n}} sT^n\right)(\phi_\lambda^t x) + (1-\lambda)^{-\frac{p}{n}} \Phi\left((1-\lambda)^{\frac{1}{n}} sT^n\right)(\psi_\lambda^t x) \quad (22)$$

for all $x \in \mathbb{R}^n$.

2. Homogeneity: For $y \in \{e_1, e_2\}^\perp$ (22) becomes

$$\Phi(sT^n)(y) = \lambda^{-\frac{p}{n}} \Phi\left(\lambda^{\frac{1}{n}} sT^n\right)(y) + (1-\lambda)^{-\frac{p}{n}} \Phi\left((1-\lambda)^{\frac{1}{n}} sT^n\right)(y).$$

Replace s with $s^{\frac{1}{n}}$ in the above equation and define $g(s) = \Phi\left(s^{\frac{1}{n}} T^n\right)(y)$. Then we have

$$g(s) = \lambda^{-\frac{p}{n}} g(\lambda s) + (1-\lambda)^{-\frac{p}{n}} g((1-\lambda)s).$$

Let $a, b > 0$. We set $s = a + b$ and $\lambda = \frac{a}{a+b}$ to get

$$g(a+b) = \left(\frac{a}{a+b}\right)^{-\frac{p}{n}} g(a) + \left(\frac{b}{a+b}\right)^{-\frac{p}{n}} g(b)$$

and hence

$$(a+b)^{-\frac{p}{n}} g(a+b) = a^{-\frac{p}{n}} g(a) + b^{-\frac{p}{n}} g(b).$$

We see that $s \mapsto s^{-\frac{p}{n}} g(s)$ solves Cauchy's functional equation for $s > 0$. By assumption there is a bounded open interval I_y such that $g(I_y)$ is not dense in \mathbb{R} . It follows that $s \mapsto s^{-\frac{p}{n}} g(s)$ is linear. This implies $s^{-\frac{p}{n}} g(s) = sg(1)$ and hence $g(s) = s^{1+\frac{p}{n}} g(1)$. The definition of g yields

$$\Phi(sT^n)(y) = g(s^n) = s^{n+p} g(1) = s^{n+p} \Phi(T^n)(y).$$

Since $n \geq 3$ and since we can do the above calculation for any two standard basis vectors, we obtain in particular

$$\Phi(sT^n)(\pm e_i) = s^{n+p} \Phi(T^n)(\pm e_i) \quad \text{for } i = 1, \dots, n. \quad (23)$$

3. Constants: Let $i \in \{1, \dots, n\}$. Since $n \geq 3$, we can find a permutation of the coordinates $\phi \in \text{SL}(n)$ such that $\phi^t e_1 = e_i$. It follows that

$$\Phi(T^n)(e_i) = \Phi(T^n)(\phi^t e_1) = \Phi(\phi T^n)(e_1) = \Phi(T^n)(e_1). \quad (24)$$

Similarly we get $\Phi(T^n)(-e_i) = \Phi(T^n)(-e_1)$. Set

$$c_1 = \frac{\Gamma(p+1+n)}{\Gamma(p+1)} \Phi(T^n)(e_1) \quad \text{and} \quad c_2 = \frac{\Gamma(p+1+n)}{\Gamma(p+1)} \Phi(T^n)(-e_1). \quad (25)$$

4. Induction: We are now going to show by induction on the number m of coordinates of x not equal to zero that

$$\Phi(sT^n)(x) = c_1 h\left(M_p^+(sT^n), x\right)^p + c_2 h\left(M_p^-(sT^n), x\right)^p \quad (26)$$

for $s > 0$ and for all $x \in \mathbb{R}^n$. Note that since $P \mapsto c_1 h \left(M_p^+(P), \cdot \right)^p + c_2 h \left(M_p^-(P), \cdot \right)^p$ satisfies the assumptions of the theorem it also satisfies (22) and (23).

The case $m = 0$ is trivial. The case $m = 1$ is also easy to verify with (23), (24), (25), (7) and (8). Now, let $m \geq 2$. Without loss of generality assume that $x_1, x_2 \neq 0$ and $|x_1| \geq |x_2|$. Since functions in $C_p(\mathbb{R}^n)$ are continuous, we can further assume that $|x_1| > |x_2|$.

First consider the case that x_1 and x_2 have different signs. Set $\lambda = \frac{x_1}{x_1 - x_2} \in (0, 1)$ and calculate

$$\begin{aligned}\phi_\lambda^t x &= x_1 e_1 + x_1(1 - \lambda)e_2 + x_2 \lambda e_2 + x_3 e_3 + \dots + x_n e_n \\ &= x_1 e_1 + x_3 e_3 + \dots + x_n e_n.\end{aligned}$$

Similarly we have

$$\psi_\lambda^t x = (x_2 e_2 + x_3 e_3 + \dots + x_n e_n).$$

Using (22) and the induction hypotheses gives the desired result.

Now consider the case that x_1, x_2 have the same sign. Set $\lambda = 1 - \frac{x_2}{x_1} \in (0, 1)$ and calculate

$$\begin{aligned}\phi_\lambda^t (x_1 e_1 + x_3 e_3 + \dots + x_n e_n) &= x_1 e_1 + x_1(1 - \lambda)e_2 + x_3 e_3 + \dots + x_n e_n \\ &= x_1 e_1 + x_2 e_2 + x_3 e_3 + \dots + x_n e_n \\ &= x\end{aligned}$$

or equivalently

$$\phi_\lambda^{-t} x = x_1 e_1 + x_3 e_3 + \dots + x_n e_n.$$

Similarly we calculate

$$\psi_\lambda^t \phi_\lambda^{-t} x = x_1(1 - \lambda)e_1 + x_3 e_3 + \dots + x_n e_n.$$

Using (22) with x replaced by $\phi_\lambda^{-t} x$ and using the induction hypotheses gives the desired result.

This completes the induction and proves (26) or equivalently (19). \square

We now use Theorem 4.1 to rule out the existence of certain valuations. This will be needed in the induction step in the proof of Theorem 4.4.

4.2 Lemma. *Let $n \geq 2$. If $\Phi: \mathcal{P}_o^n \rightarrow C_p(\mathbb{R}^n)$ is a simple $\text{GL}(n)$ -covariant valuation which is continuous at the line segment $[0, e_1]$, then $\Phi = 0$.*

Proof. First note that the $\text{GL}(n)$ -covariance implies p -homogeneity. For $n \geq 3$ the assertion follows directly from Theorem 4.1, since $P \mapsto h \left(M_p^+(P), \cdot \right)^p$ and $P \mapsto h \left(M_p^-(P), \cdot \right)^p$ are both $(n + p)$ -homogeneous.

Only the case $n = 2$ remains. Using the $\text{GL}(n)$ -covariance and Lemma 2.4 we see that Φ is determined by its values on T^2 . The $\text{GL}(n)$ -covariance and the simplicity of Φ imply

$$\Phi(T^2)(x) = \Phi(T^2)(\phi_\lambda^t x) + \Phi(T^2)(\psi_\lambda^t x). \quad (27)$$

Similar to the steps 3 and 4 in the proof of Theorem 4.1, we see that Φ is determined by the two values $\Phi(T^2)(\pm e_1)$.

Now notice that E_p^+ takes the same values as I_p^+ for all $P \in \mathcal{P}_o^2$ with $\dim P \leq 1$. Therefore

$$P \mapsto h\left(I_p^+ P, \cdot\right)^p - h\left(E_p^+ P, \cdot\right)^p$$

is a simple $\text{GL}(n)$ -covariant valuation. The same holds for

$$P \mapsto h\left(I_p^- P, \cdot\right)^p - h\left(E_p^- P, \cdot\right)^p.$$

Using (15) we see that Φ is a linear combination of these two operators. Since the only operator in the linear hull of these operators which is continuous at the line segment $[0, e_1]$ is $\Phi = 0$ (see Lemma 3.1), the assertion follows. \square

The next lemma will also be needed in the proof of Theorem 4.4. It implies that an $\text{SL}(n)$ -covariant operator $\Phi: \mathcal{P}_o^n \rightarrow \mathcal{K}_o^n$ maps a convex polytope which is contained in some linear subspace to a convex body which is contained in the same linear subspace.

4.3 Lemma. *Let $n \geq 2$. If $\Phi: \mathcal{P}_o^n \rightarrow C_p(\mathbb{R}^n)$ is $\text{SL}(n)$ -covariant, then*

$$\Phi(P)(x) = \Phi(P)(\pi_P x)$$

for all $P \in \mathcal{P}_o^n$ and $x \in \mathbb{R}^n$, where π_P denotes the orthogonal projection onto $\text{lin } P$.

Proof. For $\dim P = n$ there is nothing to show. For $\dim P = 0$, i.e. $P = \{o\}$, we have

$$\Phi P = \Phi(\phi P) = \Phi(P) \circ \phi^t$$

for all $\phi \in \text{SL}(n)$. Since $n \geq 2$, ΦP must be constant.

Now let $d = \dim P$ with $0 < d < n$. Using the $\text{SL}(n)$ -covariance we can assume without loss of generality that $P \subseteq \{e_1, \dots, e_d\}$. Define $\phi \in \text{SL}(n)$ by

$$\phi = \begin{pmatrix} I' & A \\ 0 & I'' \end{pmatrix},$$

where $A \in \mathbb{R}^{d \times (n-d)}$ is an arbitrary matrix, $0 \in \mathbb{R}^{(n-d) \times d}$ is the zero matrix and where $I' \in \mathbb{R}^{d \times d}$ and $I'' \in \mathbb{R}^{(n-d) \times (n-d)}$ are identity matrices. Since $\phi P = P$ and since Φ is $\text{SL}(n)$ -covariant, we get

$$\Phi P = \Phi(\phi P) = \Phi(P) \circ \phi^t. \quad (28)$$

Write $x = (x', x'') \in \mathbb{R}^d \times \mathbb{R}^{n-d}$. Since ΦP is continuous, we can assume that x' is not zero. Note that

$$\phi^t x = \begin{pmatrix} I' & 0^t \\ A^t & I'' \end{pmatrix} \cdot \begin{pmatrix} x' \\ x'' \end{pmatrix} = \begin{pmatrix} x' \\ A^t x' + x'' \end{pmatrix}. \quad (29)$$

Because we can choose A such that $A^t x' + x''$ is zero, the assertion follows from (28) and (29). \square

Now we are able to classify all $\text{SL}(n)$ -covariant valuations from \mathcal{P}_o^n to $C_p(\mathbb{R}^n)$ which satisfy certain continuity properties.

4.4 Theorem. *Let $n \geq 3$ and let $\Phi: \mathcal{P}_o^n \rightarrow C_p(\mathbb{R}^n)$ be an $\text{SL}(n)$ -covariant valuation. Assume further that for every $y \in \mathbb{R}^n$ there exists a bounded open interval $I_y \subseteq (0, +\infty)$ such that $\{\Phi(sT^n)(y) : s \in I_y\}$ is not dense in \mathbb{R} . Also assume that Φ is continuous at the line segment $[0, e_1]$. Then there exist constants $c_1, c_2, c_3, c_4 \in \mathbb{R}$ such that*

$$\Phi P = c_1 h\left(M_p^+ P, \cdot\right)^p + c_2 h\left(M_p^- P, \cdot\right)^p + c_3 h\left(I_p^+ P, \cdot\right)^p + c_4 h\left(I_p^- P, \cdot\right)^p \quad (30)$$

for all $P \in \mathcal{P}_o^n$.

Proof. Lemma 4.3 and the p -homogeneity of functions in $C_p(\mathbb{R}^n)$ show that

$$\Phi([o, e_1])(x) = \Phi([o, e_1])(x_1 e_1) = |x_1|^p \Phi([o, e_1])(\text{sgn}(x_1) e_1) \quad (31)$$

for all $x \in \mathbb{R}^n$. Set $c_3 = \Phi([o, e_1])(e_1)$ and $c_4 = \Phi([o, e_1])(-e_1)$. Define $\Psi: \mathcal{P}_o^n \rightarrow C_p(\mathbb{R}^n)$ by

$$\Psi P = \Phi P - c_3 h\left(I_p^+ P, \cdot\right)^p - c_4 h\left(I_p^- P, \cdot\right)^p \quad (32)$$

for all $P \in \mathcal{P}_o^n$. Note that Ψ is also an $\text{SL}(n)$ -covariant valuation. If we can show that Ψ is simple, then the assertion follows from Theorem 4.1.

We need to prove that $\Psi P = 0$ for all $P \in \mathcal{P}_o^n$ with $\dim P \leq n - 1$. Using the $\text{SL}(n)$ -covariance we can assume without loss of generality that $P \subseteq \text{lin}\{e_1, \dots, e_{n-1}\}$. We will use induction on $d = 1, \dots, n - 1$ to show that $\Psi P = 0$ for all convex polytopes $P \subseteq \text{lin}\{e_1, \dots, e_d\}$. Define $\hat{\Psi}: \mathcal{P}_o^d \rightarrow C_p(\mathbb{R}^d)$ by

$$\hat{\Psi} P = \Psi(\iota_d P) \circ \iota_d \quad (33)$$

for all $P \in \mathcal{P}_o^d$, where ι_d denotes the natural embedding of \mathbb{R}^d in \mathbb{R}^n . It is easy to see that $\hat{\Psi}$ is a $\text{GL}(d)$ -covariant valuation. Since Ψ is $\text{SL}(n)$ -covariant, we have $\Psi(\{o\}) = 0$ by Lemma 4.3. For $d = 1$ the induction statement follows from (31), (6) and the $\text{GL}(d)$ -covariance. For $2 \leq d \leq n - 1$ the induction statement follows from the induction hypothesis, Lemma 4.2 and Lemma 4.3. This finishes the induction and completes the proof of the theorem. \square

Finally we can prove our desired result about continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuations on \mathcal{K}_o^n . This is one direction of the first main theorem from the introduction. The other direction is trivial.

4.5 Corollary. *Let $n \geq 3$. If $\Phi: \mathcal{K}_o^n \rightarrow \mathcal{K}_o^n$ is a continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuation, then there exist constants $c_1, c_2, c_3, c_4 \geq 0$ such that*

$$\Phi K = c_1 M_p^+ K + c_2 M_p^- K + c_3 I_p^+ K + c_4 I_p^- K$$

for all $K \in \mathcal{K}_o^n$.

Proof. The map

$$P \mapsto h(\Phi P, \cdot)^p, \quad P \in \mathcal{P}_o^n$$

satisfies the assumptions of Theorem 4.4. Thus, we get constants $d_1, d_2, d_3, d_4 \in \mathbb{R}$ such that

$$h(\Phi P, \cdot)^p = d_1 h(M_p^+ P, \cdot)^p + d_2 h(M_p^- P, \cdot)^p + d_3 h(I_p^+ P, \cdot)^p + d_4 h(I_p^- P, \cdot)^p$$

holds for all $P \in \mathcal{P}_o^n$. By continuity this is true for all $K \in \mathcal{K}_o^n$. It remains to show that $d_1, d_2, d_3, d_4 \geq 0$. To this end consider for fixed $K \in \mathcal{K}^n$ and $x \in \mathbb{R}^n$ the map $s \mapsto h(\Phi(sK), x)^p$, $s > 0$. Using the homogeneity of the operators M_p^+ , M_p^- , I_p^+ and I_p^- we get

$$\begin{aligned} 0 &\leq h(\Phi(sK), x)^p \\ &= \left(d_1 h(M_p^+ K, x)^p + d_2 h(M_p^- K, x)^p \right) s^{n+p} + \left(d_3 h(I_p^+ K, x)^p + d_4 h(I_p^- K, x)^p \right) s^p. \end{aligned}$$

Dividing this equation by s^p and letting $s \rightarrow 0$ we see that

$$0 \leq d_3 h(I_p^+ K, x)^p + d_4 h(I_p^- K, x)^p.$$

Setting $K = [o, e_1]$ and $x = \pm e_1$ and using (6) shows that $d_3, d_4 \geq 0$. Similarly we see that $d_1, d_2 \geq 0$. Defining $c_i = \sqrt[p]{d_i}$ for $i = 1, \dots, 4$ finishes the proof. \square

5 Main Results on \mathcal{K}^n

In this section our goal is the classification of all continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuations on \mathcal{K}^n . We start with a classification of valuations from \mathcal{P}^n to $C_p(\mathbb{R}^n)$ with the additional assumption that the valuation is almost simple. Here we call a valuation $\Phi: \mathcal{Q}^n \rightarrow A$ almost simple, if $\Phi K = 0$ for all $K \in \mathcal{Q}^n$ with $\dim K \leq n-2$ and for all $K \in \mathcal{Q}^n$ with $\dim K = n-1$ and $o \in \text{aff } K$.

5.1 Theorem. *Let $n \geq 3$ and let $\Phi: \mathcal{P}^n \rightarrow C_p(\mathbb{R}^n)$ be an almost simple $\text{SL}(n)$ -covariant valuation. Assume further that for every $y \in \mathbb{R}^n$ there exists a bounded open interval $I_y \subseteq (0, +\infty)$ such that $\{\Phi(sT^n)(y) : s \in I_y\}$ is not dense in \mathbb{R} and that for every $y \in \mathbb{R}^n$ there exists a bounded open interval $J_y \subseteq (0, +\infty)$ such that $\{\Phi(s\tilde{T}^{n-1})(y) : s \in J_y\}$ is not dense in \mathbb{R} . Then there exist constants $c_1, c_2, c_3, c_4 \in \mathbb{R}$ such that*

$$\Phi P = c_1 h(M_p^+ P, \cdot)^p + c_2 h(M_p^- P, \cdot)^p + c_3 h(\hat{M}_p^+ P, \cdot)^p + c_4 h(\hat{M}_p^- P, \cdot)^p$$

for all $P \in \mathcal{P}^n$.

Proof. By replacing T^n with \tilde{T}^{n-1} and by replacing (7) and (8) with (11) and (12), respectively, in the proof of Theorem 4.1 we see that there exist constants c_3, c_4 such that

$$\Phi(s\tilde{T}^{n-1}) = c_3 h(\hat{M}_p^+(s\tilde{T}^{n-1}), \cdot)^p + c_4 h(\hat{M}_p^-(s\tilde{T}^{n-1}), \cdot)^p$$

for $s > 0$. Note that the constants are given by

$$c_3 = \frac{\Gamma(p+1+n)}{\Gamma(p+1)} \Phi(\tilde{T}^{n-1})(e_1) \quad \text{and} \quad c_4 = \frac{\Gamma(p+1+n)}{\Gamma(p+1)} \Phi(\tilde{T}^{n-1})(-e_1).$$

Define $\Psi: \mathcal{P}^n \rightarrow C_p(\mathbb{R}^n)$ by

$$\Psi P = \Phi P - c_3 h(\hat{M}_p^+ P, \cdot)^p - c_4 h(\hat{M}_p^- P, \cdot)^p$$

for all $P \in \mathcal{P}^n$. Note that Ψ is an $\text{SL}(n)$ -covariant valuation. We use $\Psi(s\tilde{T}^{n-1}) = 0$, the $\text{SL}(n)$ -covariance of Ψ , Theorem 2.1 and the assumption that Φ is almost simple to see that Ψ is simple. Now Theorem 4.1 implies that there exist constants $c_1, c_2 \in \mathbb{R}$ such that

$$\Psi P = c_1 h(M_p^+ P, \cdot)^p + c_2 h(M_p^- P, \cdot)^p \quad (34)$$

for all $P \in \mathcal{P}_o^n$. Because M_p^+ and M_p^- are simple valuations on \mathcal{P}^n , Lemma 2.5 implies that (34) holds for all $P \in \mathcal{P}^n$. Using the definition of Ψ finishes the proof. \square

The next lemma is the analog of Lemma 4.2 for \mathcal{P}^n and will be needed in the induction step in the proof of Theorem 5.4. Again, it will rule out the existence of certain valuations.

5.2 Lemma. *Let $n \geq 2$. If $\Phi: \mathcal{P}_o^n \rightarrow C_p(\mathbb{R}^n)$ is an almost simple $\text{GL}(n)$ -covariant valuation which is continuous at the line segment $[0, e_1]$, then $\Phi = 0$.*

Proof. First note that the $\text{GL}(n)$ -covariance implies p -homogeneity. For $n \geq 3$ the assertion follows directly from Theorem 5.1, since $P \mapsto h(M_p^+ P, \cdot)^p$, $P \mapsto h(M_p^- P, \cdot)^p$, $P \mapsto h(\hat{M}_p^+ P, \cdot)^p$ and $P \mapsto h(\hat{M}_p^- P, \cdot)^p$ are all $(n+p)$ -homogeneous.

Only the case $n = 2$ remains to be proved. Similar to the steps 3 and 4 in the proof of Theorem 4.1, we see that $\Phi \tilde{T}^1$ is determined by the two values $\Phi(\tilde{T}^1)(\pm e_1)$. Now notice that

$$P \mapsto h(I_p^+ P, \cdot)^p - h(E_p^+ P, \cdot)^p \quad \text{and} \quad P \mapsto h(I_p^- P, \cdot)^p - h(E_p^- P, \cdot)^p,$$

are almost simple $\text{GL}(n)$ -covariant valuations. Using (16), the $\text{GL}(n)$ -covariance and Theorem 2.1 we see that by subtracting a suitable linear combination of these two operators from Φ we get a simple $\text{GL}(n)$ -covariant valuation Ψ . Using the same arguments as in the proof of Theorem 4.1 and using Lemma 2.5 we see that Ψ is determined by the two values $\Phi(T^2)(\pm e_1)$. Since

$$P \mapsto h(I_p^+ P, \cdot)^p - h(E_p^+ P, \cdot)^p + J_p^+ P - F_p^+ P$$

and

$$P \mapsto h(I_p^- P, \cdot)^p - h(E_p^- P, \cdot)^p + J_p^- P - F_p^- P$$

are simple $\text{GL}(n)$ -covariant valuations, we can use (17) to conclude that Ψ is a linear combination of these two operators. Therefore, Φ is a linear combination of the four operators above. Since the only operator in the linear hull of these operators which is continuous at $[0, e_1]$ is $\Phi = 0$ (see Lemma 3.2), the assertion follows. \square

5.3 Lemma. *Let $n \geq 2$. If $\Phi: \mathcal{P}^n \rightarrow C_p(\mathbb{R}^n)$ is $\text{SL}(n)$ -covariant, then $\Phi(P)(x) = \Phi(P)(\pi_P x)$ for all $P \in \mathcal{P}^n$ and $x \in \mathbb{R}^n$, where π_P denotes the orthogonal projection onto $\text{lin } P$.*

Proof. The proof is similar to the proof of Lemma 4.3. \square

Now we are able to classify all $\text{SL}(n)$ -covariant valuations from \mathcal{P}^n to $C_p(\mathbb{R}^n)$ which satisfy certain continuity properties.

5.4 Theorem. *Let $n \geq 3$ and let $\Phi: \mathcal{P}^n \rightarrow C_p(\mathbb{R}^n)$ be an $\text{SL}(n)$ -covariant valuation. Assume further that for every $y \in \mathbb{R}^n$ there exists a bounded open interval $I_y \subseteq (0, +\infty)$ such that $\{\Phi(sT^n)(y) : s \in I_y\}$ is not dense in \mathbb{R} and that for every $y \in \mathbb{R}^n$ there exists a bounded open interval $J_y \subseteq (0, +\infty)$ such that $\{\Phi(s\tilde{T}^{n-1})(y) : s \in J_y\}$ is not dense in \mathbb{R} . Also assume that Φ is continuous at the line segment $[0, e_1]$. Then there exist constants $c_i \in \mathbb{R}$, $i = 1, \dots, 8$ such that*

$$\begin{aligned} \Phi P = & c_1 h(M_p^+ P, \cdot)^p + c_2 h(M_p^- P, \cdot)^p + c_3 h(\hat{M}_p^+ P, \cdot)^p + c_4 h(\hat{M}_p^- P, \cdot)^p \\ & + c_5 h(I_p^+ P, \cdot)^p + c_6 h(I_p^- P, \cdot)^p + c_7 J_p^+ P + c_8 J_p^- P \end{aligned}$$

for all $P \in \mathcal{P}^n$.

Proof. Lemma 5.3 and the p -homogeneity of the functions in $C_p(\mathbb{R}^n)$ show that

$$\Phi([o, e_1])(x) = \Phi([o, e_1])(x_1 e_1) = |x_1|^p \Phi([o, e_1])(\text{sgn}(x_1) e_1) \quad (35)$$

and

$$\Phi([e_1, 2e_1])(x) = |x_1|^p \Phi([e_1, 2e_1])(\text{sgn}(x_1) e_1) \quad (36)$$

for all $x \in \mathbb{R}^n$. Set $c_5 = \Phi([o, e_1])(e_1)$, $c_6 = \Phi([o, e_1])(-e_1)$, $c_7 = \Phi([e_1, 2e_1])(e_1) - c_5 2^p$ and $c_8 = \Phi([e_1, 2e_1])(-e_1) - c_6 2^p$. Define $\Psi: \mathcal{P}^n \rightarrow C_p(\mathbb{R}^n)$ by

$$\Psi P = \Phi P - c_5 h(I_p^+ P, \cdot)^p - c_6 h(I_p^- P, \cdot)^p - c_7 J_p^+ P - c_8 J_p^- P \quad (37)$$

for all $P \in \mathcal{P}^n$. Note that Ψ is also an $\text{SL}(n)$ -covariant valuation. If we can show that Ψ is almost simple, then the assertion follows from Theorem 5.1.

We need to prove that $\Psi P = 0$ for all $P \in \mathcal{P}^n$ with $\dim P \leq n - 2$ and for all $P \in \mathcal{P}^n$ with $\dim P = n - 1$ and $o \in \text{aff } P$. Using the $\text{SL}(n)$ -covariance we can assume without loss of generality that $P \subseteq \text{lin}\{e_1, \dots, e_{n-1}\}$. We will use induction on $d = 1, \dots, n - 1$ to show that $\Psi P = 0$ for all convex polytopes $P \subseteq \text{lin}\{e_1, \dots, e_d\}$. Define $\hat{\Psi}: \mathcal{P}^d \rightarrow C_p(\mathbb{R}^d)$ by

$$\hat{\Psi} P = \Psi(\iota_d P) \circ \iota_d \quad (38)$$

for all $P \in \mathcal{P}^d$, where ι_d denotes the natural embedding of \mathbb{R}^d in \mathbb{R}^n . It is easy to see that $\hat{\Psi}$ is a $\text{GL}(d)$ -covariant valuation. Since Ψ is $\text{SL}(n)$ -covariant, we have $\Psi(\{o\}) = 0$ by Lemma 5.3. For $d = 1$ the induction statement follows from (35), (36), (6), (9), (10), the $\text{GL}(d)$ -covariance and Lemma 5.3. For $2 \leq d \leq n - 1$ the induction statement follows from the induction hypothesis, Lemma 5.2 and Lemma 5.3. This finishes the induction and completes the proof of the theorem. \square

Finally we can prove our desired result about continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuations on \mathcal{K}^n . This is one direction of the second main theorem from the introduction. The other direction is trivial.

5.5 Corollary. *Let $n \geq 3$. If $\Phi: \mathcal{K}^n \rightarrow \mathcal{K}_o^n$ is a continuous $\text{SL}(n)$ -covariant L_p -Minkowski valuation, then there exist constants $c_1, c_2, c_3, c_4, c_5, c_6 \geq 0$ such that*

$$\Phi K = c_1 M_p^+ K +_p c_2 M_p^- K +_p c_3 \hat{M}_p^+ K +_p c_4 \hat{M}_p^- K +_p c_5 I_p^+ K +_p c_6 I_p^- K$$

for all $K \in \mathcal{K}^n$.

Proof. The map

$$P \mapsto h(\Phi P, \cdot)^p, \quad P \in \mathcal{P}_o^n$$

satisfies the assumptions of Theorem 5.4. Thus, we get constants $d_1, \dots, d_8 \in \mathbb{R}$ such that

$$\begin{aligned} h(\Phi P, \cdot)^p &= d_1 h(M_p^+ P, \cdot)^p + d_2 h(M_p^- P, \cdot)^p + d_3 h(\hat{M}_p^+ P, \cdot)^p + d_4 h(\hat{M}_p^- P, \cdot)^p \\ &\quad + d_5 h(I_p^+ P, \cdot)^p + d_6 h(I_p^- P, \cdot)^p + d_7 J_p^+ P + d_8 J_p^- P \end{aligned}$$

holds for all $P \in \mathcal{P}^n$. By continuity this holds for all $K \in \mathcal{K}^n$. It remains to show that $d_1, \dots, d_6 \geq 0$ and that $d_7, d_8 = 0$. Similar to the proof of Corollary 4.5 we consider the map $s \mapsto h(\Phi(sK), \cdot)$, $s > 0$ for fixed $K \in \mathcal{K}^n$ to see that both

$$\left(d_1 h(M_p^+ K, \cdot)^p + d_2 h(M_p^- K, \cdot)^p + d_3 h(\hat{M}_p^+ K, \cdot)^p + d_4 h(\hat{M}_p^- K, \cdot)^p \right)^{\frac{1}{p}}$$

and

$$\left(d_5 h(I_p^+ K, \cdot)^p + d_6 h(I_p^- K, \cdot)^p + d_7 J_p^+ K + d_8 J_p^- K \right)^{\frac{1}{p}} \quad (39)$$

are nonnegative and sublinear. Using (7), (8), (11), (12) and (6) we get that $d_1, \dots, d_6 \geq 0$. Now set $K = \text{conv}\{e_1, e_2, e_1 + e_2\}$ in (39). Inserting the directions e_1, e_2 and $e_1 + e_2$ and using the subadditivity and (13) gives us

$$(2^p d_5 + d_7)^{\frac{1}{p}} \leq (d_5)^{\frac{1}{p}} + (d_5)^{\frac{1}{p}} = 2(d_5)^{\frac{1}{p}}.$$

Therefore we get $d_7 \leq 0$. Meanwhile, setting $K = \tilde{T}^1$ in (39) and inserting the directions $e_1, e_1 + e_2$ and $2e_1 + e_2$ gives us by (14)

$$0 \leq (d_5)^{\frac{1}{p}} + (d_5 + d_7)^{\frac{1}{p}} - (2^p d_5 + d_7)^{\frac{1}{p}}.$$

The right hand side of this equation is equal to 0 for $d_7 = 0$. By differentiating the right hand side with respect to d_7 and by using $p > 1$ we see that it is strictly monotone. Therefore we get $d_7 \geq 0$. The last two arguments show that $d_7 = 0$. Similarly we see that $d_8 = 0$. Setting $c_i = \sqrt[p]{d_i}$ for $i = 1, \dots, 6$ finishes the proof. \square

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